
Principles of Communications

Lecture 5: Analog Modulation Techniques (3)

Chih-Wei Liu 劉志尉

National Chiao Tung University

cwliu@twins.ee.nctu.edu.tw

Outlines

- Linear Modulation
- Angle Modulation
- Interference
- Feedback Demodulators
- Analog Pulse Modulation
- Delta Modulation and PCM
- Multiplexing

Angle Modulation

- Modulated signals have constant amplitude; information is embedded in the **phase**.

General form: $x_c(t) = A_c \cos[\omega_c t + \phi(t)]$

- Phase deviation: $\phi(t)$

- Frequency deviation: $\frac{d\phi(t)}{dt}$

PM: $\phi(t) = K_P \cdot m(t)$ ($m(t)$ is the message.)

FM: $\frac{d\phi(t)}{dt} = K_F \cdot m(t)$

$$\phi(t) = K_F \int_{t_0}^t m(\alpha) d\alpha + \phi_0 = 2\pi f_d \int_{t_0}^t m(\alpha) d\alpha + \phi_0$$

Example of PM and FM Waveforms

$$\text{PM: } x_c(t) = A_C \cos[\omega_c t + K_p m(t)]$$

$$\text{FM: } x_c(t) = A_C \cos[\omega_c t + 2\pi f_d \int_{t_0}^t m(\alpha) d\alpha]$$

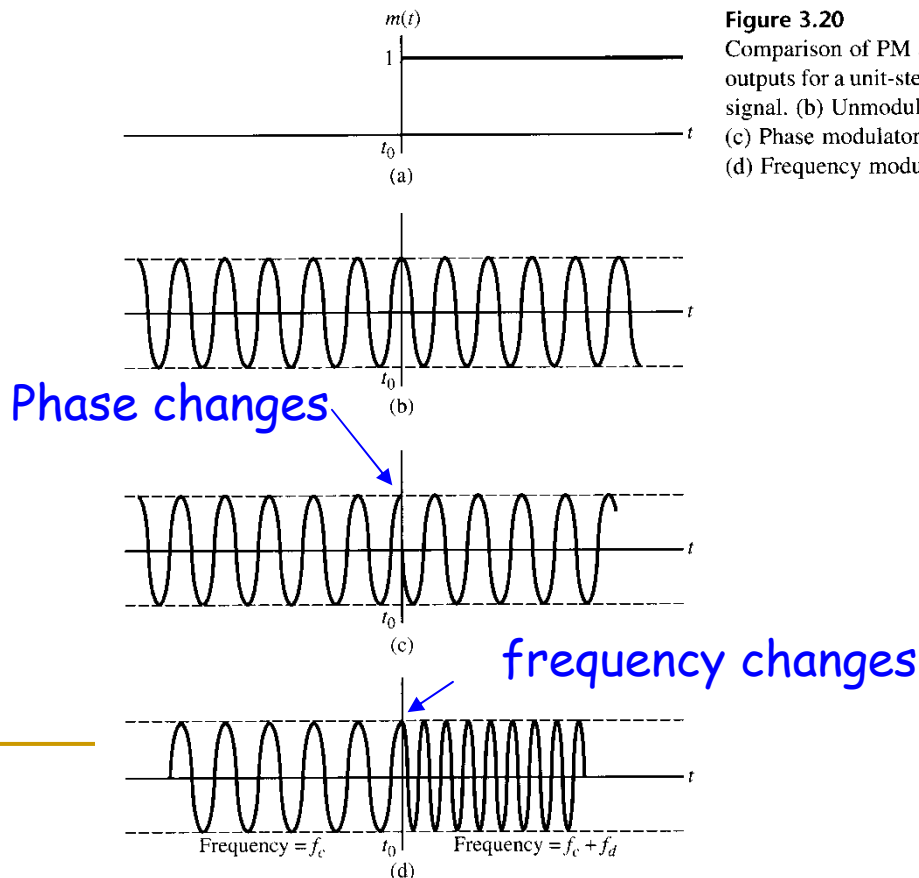


Figure 3.20
Comparison of PM and FM modulator outputs for a unit-step input. (a) Message signal. (b) Unmodulated carrier. (c) Phase modulator output ($k_p = \frac{1}{2}\pi$). (d) Frequency modulator output.

Another Example

- Sinusoidal message

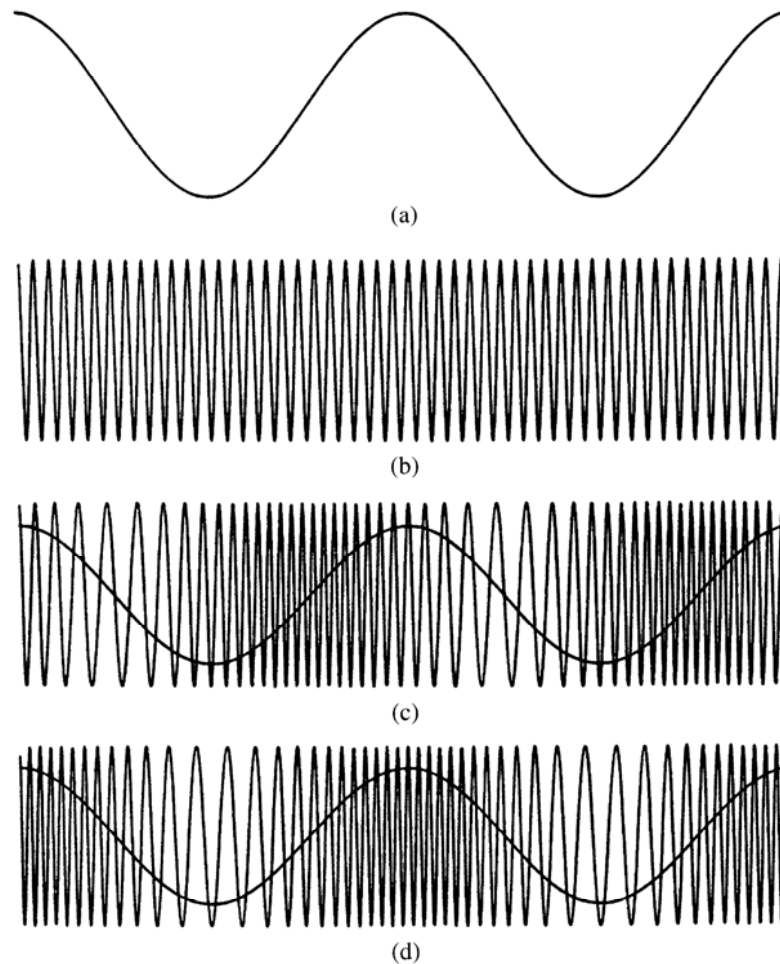


Figure 3.21

Angle modulation with sinusoidal message signal. (a) Message signal $m(t)$. (b) Unmodulated carrier $A_c \cos(2\pi f_c t)$. (c) Output of phase modulator with $m(t)$. (d) Output of frequency modulator with $m(t)$. 5

Angle Modulation Analysis

- Narrow-band modulated signals

Wide-band modulated signals

-- Message: single tone; general signal

- Narrowband Angle Modulation

$$x_c(t) = A_C \cos[\omega_c t + \varphi(t)] = \text{Re}\{A_C e^{j\omega_c t} e^{j\varphi(t)}\}$$

$$= \text{Re}\left\{A_C e^{j\omega_c t} \left(1 + j\varphi(t) + \frac{(j\varphi(t))^2}{2!} + \dots\right)\right\}$$

$$\approx \text{Re}\{A_C e^{j\omega_c t} (1 + j\varphi(t))\}$$

Taylor series expansion..

$$\Rightarrow x_c(t) \approx A_C \cos \omega_c t - A_C \varphi(t) \sin \omega_c t$$

Narrow-band Signal Generation

- Narrowband angle-mod signals ~ AM signal except that $m(t)$ multiplies a 90° phase-shifted carrier
- BW of $\phi(t) = W \rightarrow$ BW of $x_c(t) = 2W$ (*narrow!*)
-

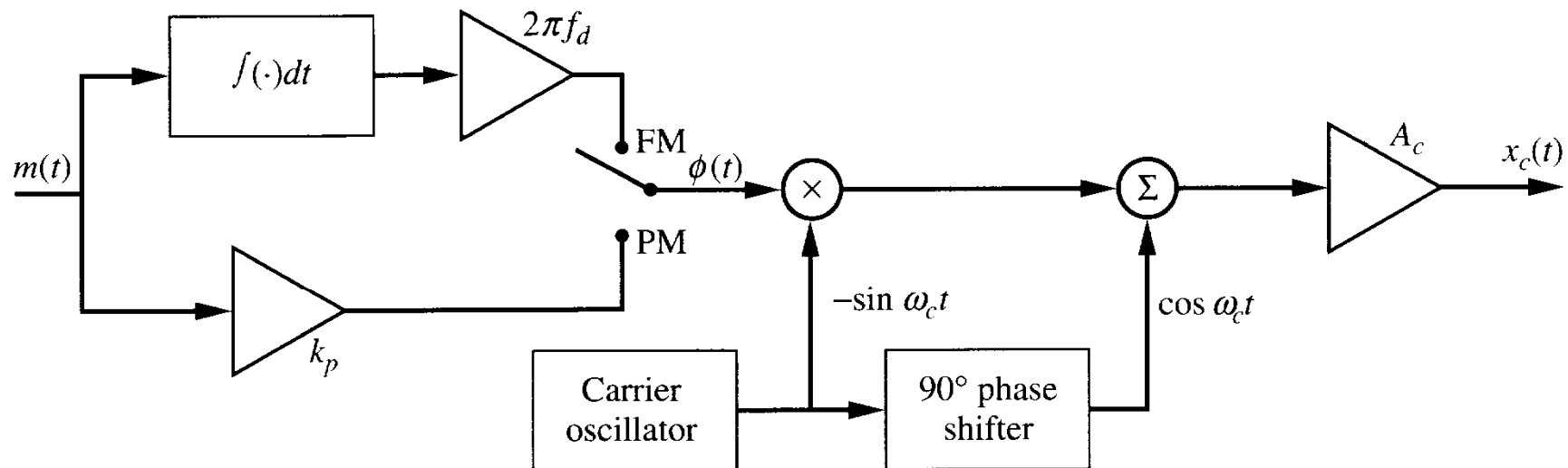


Figure 3.22
Generation of narrowband angle modulation.

Narrow-band Signal Example

- $m(t)=\cos(2 \pi f_m t)$ AM vs. PM

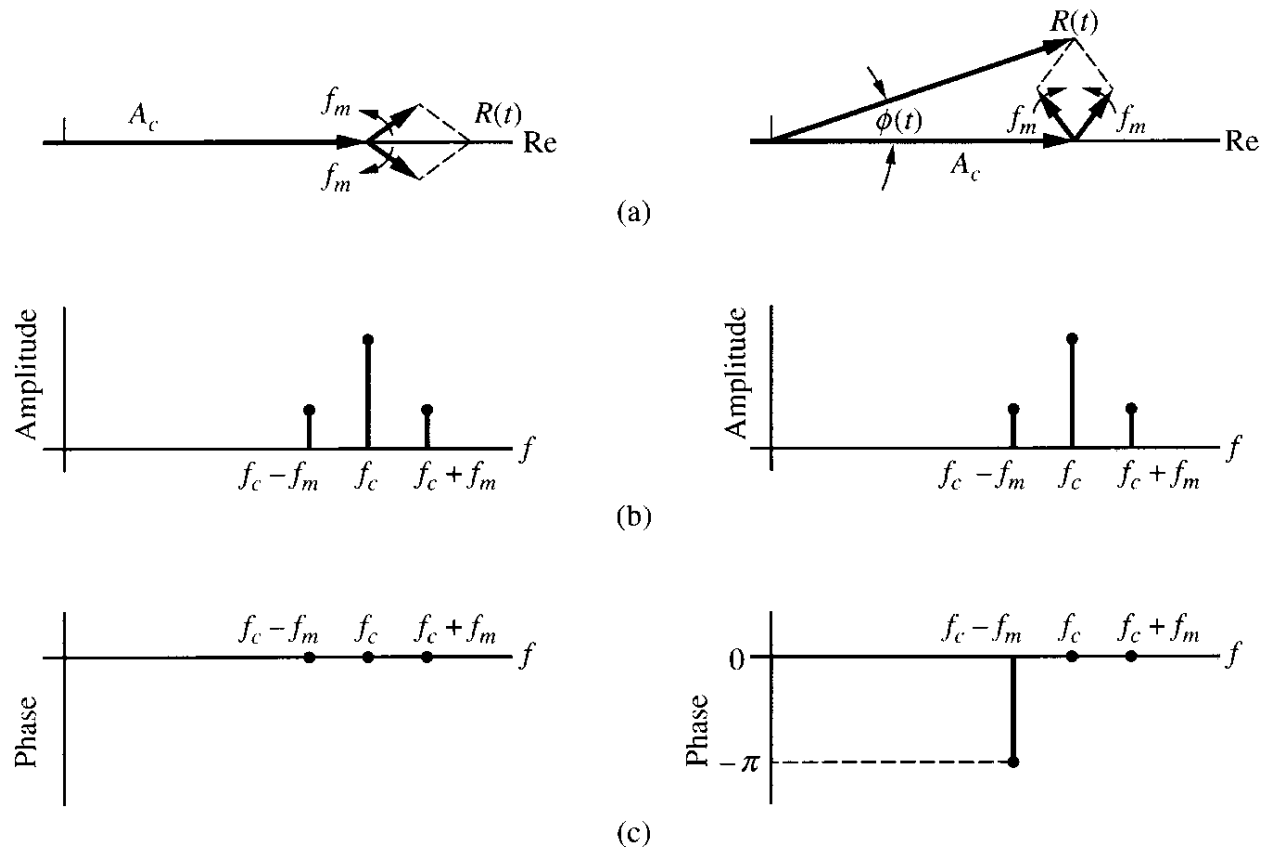


Figure 3.23

Comparison of AM and narrowband angle modulation. (a) Phasor diagrams. (b) Single-sided amplitude spectra. (c) Single-sided phase spectra.

Wide-band Angle Modulation

- The modulated signal has a much wider BW than the original message.

(A) Message is a single tone -- $m(t) = \sin(2\pi f_m t)$

- **Modulation index** β is sufficiently large

$$\text{Let } \varphi(t) = \beta \sin \omega_m t$$

→ β controls the maximum phase deviation

- Q: Why do we study the sinusoidal message?

Wide-band FM (Single Tone)

Let $\phi(t) = \beta \sin \omega_m t$.

$$x_c(t) = A_C \cos(\omega_c t + \beta \sin \omega_m t) = A_C \operatorname{Re}\{e^{j\omega_c t} e^{j\beta \sin \omega_m t}\}$$

$$\text{FS of } e^{j\beta \sin \omega_m t} \rightarrow C_n = \frac{1}{T_0} \int_0^{T_0} e^{j\beta \sin \omega_m t} e^{-jn\omega_m t} dt = \frac{\omega_m}{2\pi} \int_{-\pi/\omega_m}^{\pi/\omega_m} e^{j\beta \sin \omega_m t} e^{-jn\omega_m t} dt$$

$$= \frac{1}{2\pi} \int_{-\pi}^{\pi} e^{-j(nx - \beta \sin x)} dx \equiv J_n(\beta) \quad \text{Bessel function of the 1st kind (order } n)$$

$$e^{j\beta \sin \omega_m t} = \sum_{n=-\infty}^{\infty} J_n(\beta) \cdot e^{jn\omega_m t}$$

$$\Rightarrow x_c(t) = A_C \operatorname{Re}\{e^{j\omega_c t} \sum_{n=-\infty}^{\infty} J_n(\beta) e^{jn\omega_m t}\} = A_C \sum_{n=-\infty}^{\infty} J_n(\beta) \cos[(\omega_c + n\omega_m)t]$$

$$\Rightarrow X_c(f) = \sum_{n=-\infty}^{\infty} J_n(\beta) \delta(\omega - n\omega_m - \omega_c) + \sum_{n=-\infty}^{\infty} J_n(\beta) \delta(\omega + n\omega_m + \omega_c).$$

Bessel Function

Table 3.2 Bessel Functions

n	$\beta=0.05$	$\beta=0.1$	$\beta=0.2$	$\beta=0.3$	$\beta=0.5$	$\beta=0.7$	$\beta=1.0$	$\beta=2.0$	$\beta=3.0$	$\beta=5.0$	$\beta=7.0$	$\beta=8.0$	$\beta=10.0$
0	<u>0.999</u>	<u>0.998</u>	<u>0.990</u>	<u>0.978</u>	<u>0.938</u>	<u>0.881</u>	0.765	0.224	-0.260	-0.178	0.300	0.172	-0.246
1	0.025	0.050	0.100	<u>0.148</u>	<u>0.242</u>	<u>0.329</u>	<u>0.440</u>	<u>0.577</u>	0.339	-0.328	-0.005	0.235	0.043
2		0.001	0.005	0.011	0.031	0.059	<u>0.115</u>	0.353	<u>0.486</u>	0.047	-0.301	-0.113	0.255
3				0.001	0.003	0.007	0.020	<u>0.129</u>	0.309	0.365	-0.168	-0.291	0.058
4						0.001	0.002	0.034	<u>0.132</u>	<u>0.391</u>	0.158	-0.105	-0.220
5								0.007	0.043	0.261	0.348	0.186	-0.234
6							0.001	0.011	<u>0.131</u>	<u>0.339</u>	0.338	0.338	-0.014
7									0.003	0.053	0.234	<u>0.321</u>	0.217
8										0.018	<u>0.128</u>	0.223	<u>0.318</u>
9										0.006	0.059	<u>0.126</u>	0.292
10										0.001	0.024	0.061	0.207
11											0.008	0.026	<u>0.123</u>
12											0.003	0.010	0.063
13											0.001	0.003	0.029
14												0.001	0.012
15													0.005
16													0.002
17													0.001

FM Spectrum (Tone)

- $x_c(t)$ has a line-spectrum (FS)

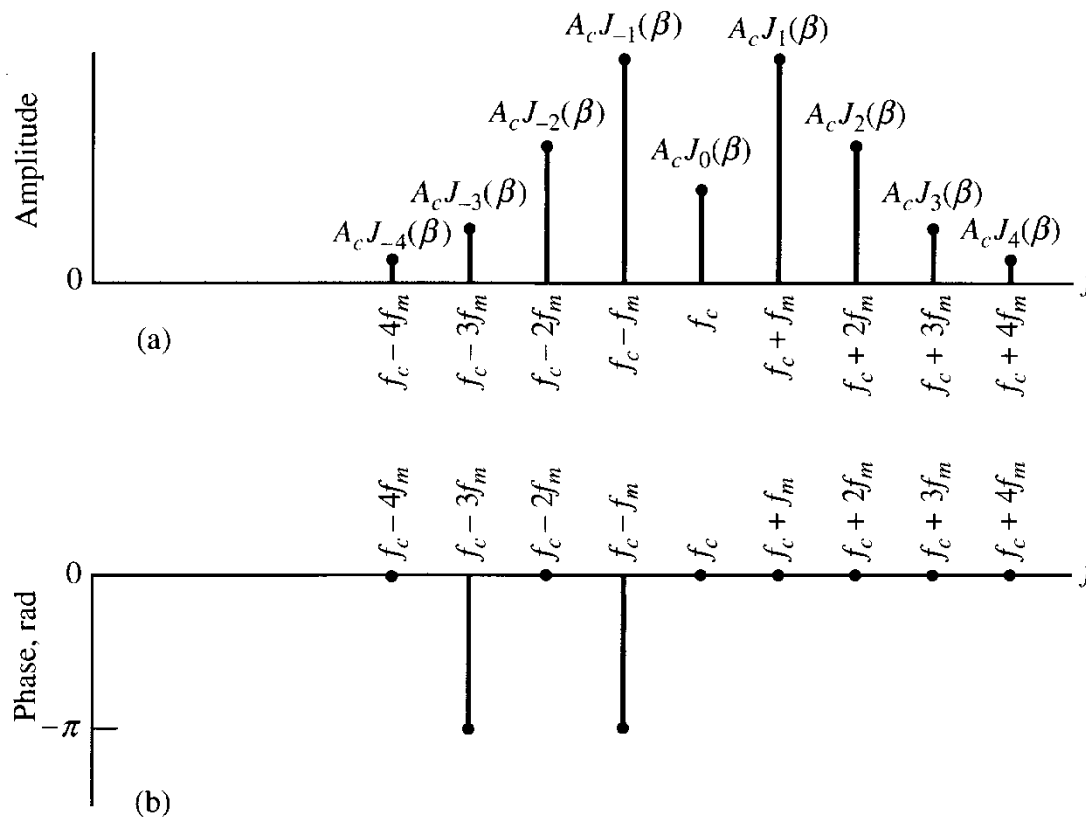


Figure 3.24

Spectra of an angle-modulated signal. (a) Single-sided amplitude spectrum. (b) Single-sided phase spectrum.

Properties of $J_n(\beta)$

1. $J_n(\beta)$ are real-valued
2. $J_{-n}(\beta) = J_n(\beta)$, n even
 $J_{-n}(\beta) = -J_n(\beta)$, n odd
3. Recursive relation: Given $J_0(\beta)$ and $J_1(\beta)$, we can derive all the $J_n(\beta)$ for $n \geq 2$.

$$J_{n+1}(\beta) = \frac{2n}{\beta} J_n(\beta) + J_{n-1}(\beta)$$

4. When β is small (narrowband FM/PM)
 $J_0(\beta) \sim 1$; $J_1(\beta) \sim \beta/2$; $J_n(\beta) \sim 0$, for $n \geq 2$

5.
$$\sum_{n=-\infty}^{\infty} J_n^2(\beta) = 1$$
 (Pf) FS representation + Parseval's Thm

$J_n(\beta)$ as a Function of β

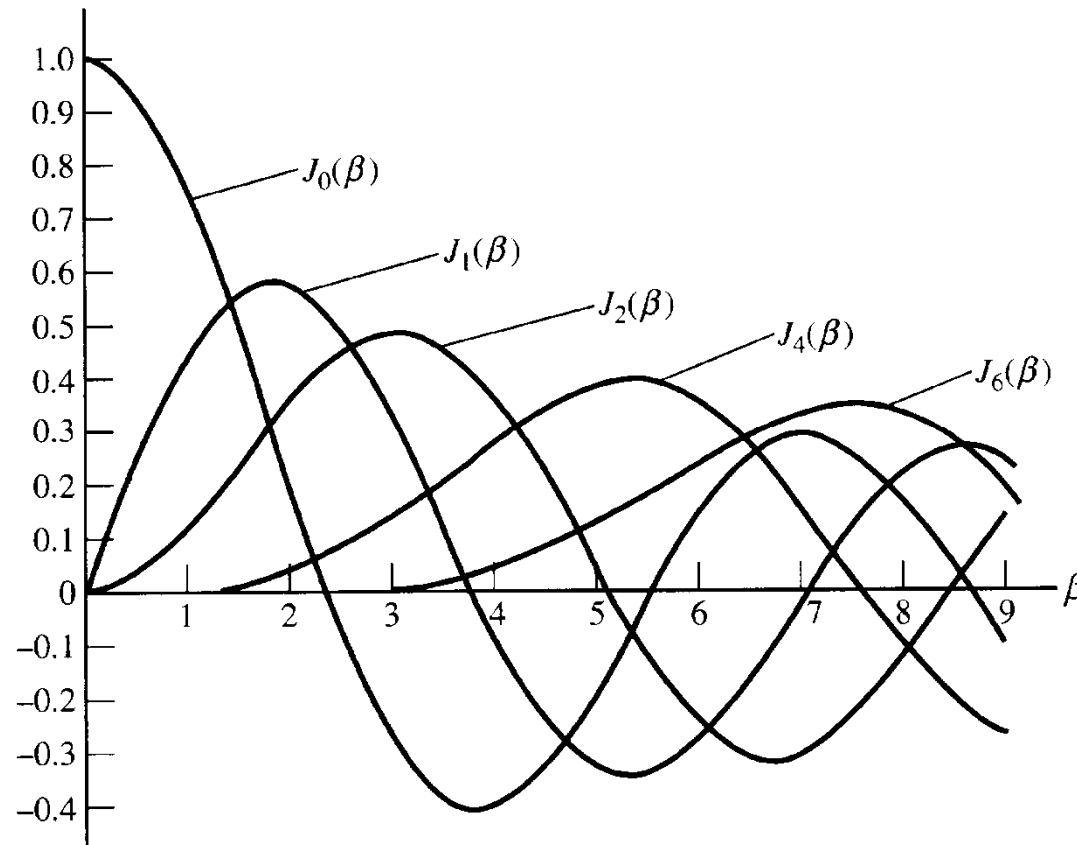


Figure 3.25

$J_n(\beta)$ as a function of β .

- **Carrier nulls:** The β values such that $J_n(\beta)=0$.

Summary

- The above analysis is based on the *sinusoidal message* assumption.

$$\varphi(t) = \beta \sin \omega_m t$$

- PM: This means $m(t) = A \sin(2\pi f_m t)$
and modulation index: β , and $K_p \equiv \beta / A$.

- FM: This means $m(t) = A \cos(2\pi f_m t)$
and modulation index: $f_d \equiv \beta \frac{\omega_m}{2\pi A} = \beta \frac{f_m}{A}$

Note:

$$\varphi(t) = 2\pi f_d \int_t m(\alpha) d\alpha = 2\pi f_d \frac{A}{\omega_m} \sin \omega_m t$$

FM Spectra Examples

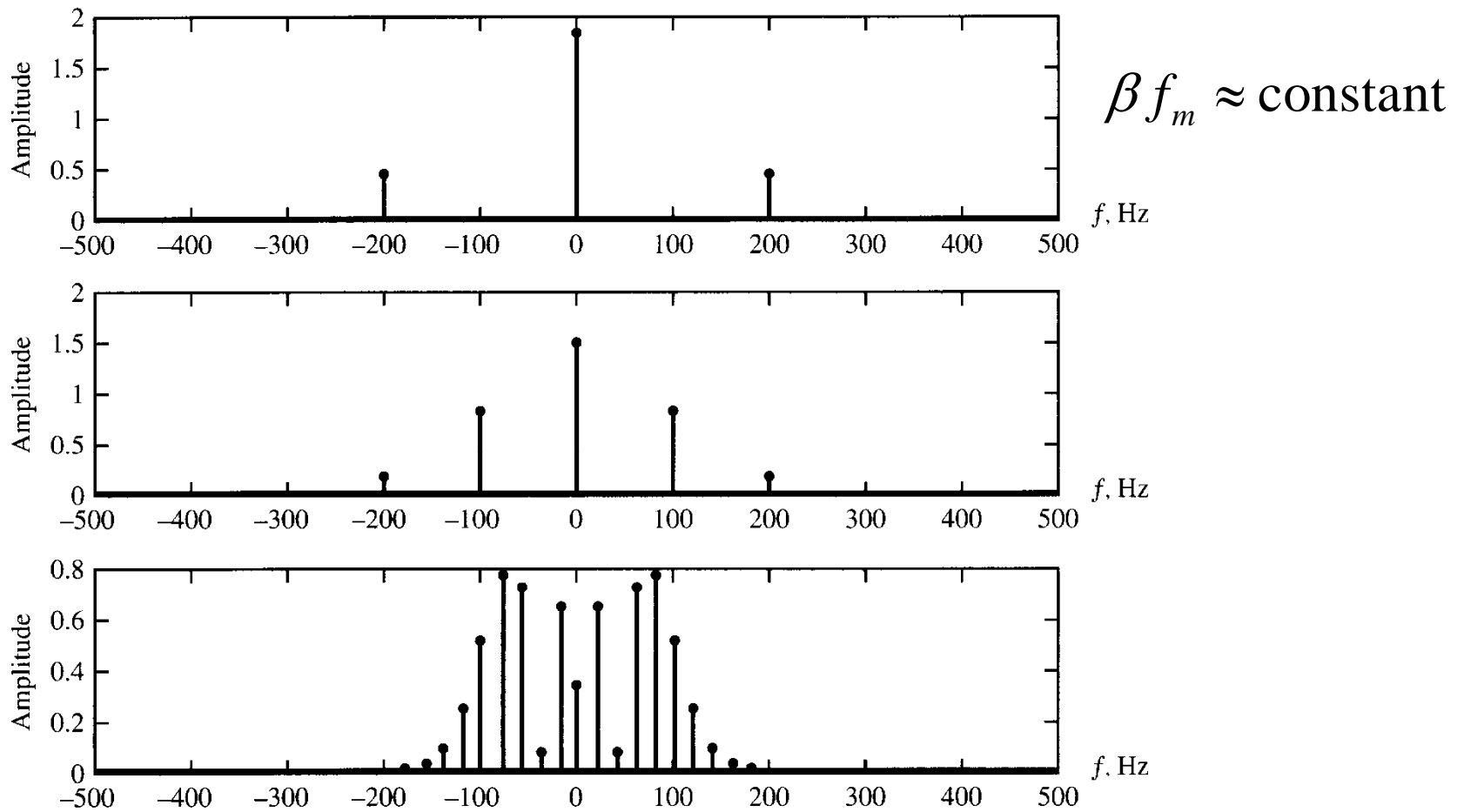
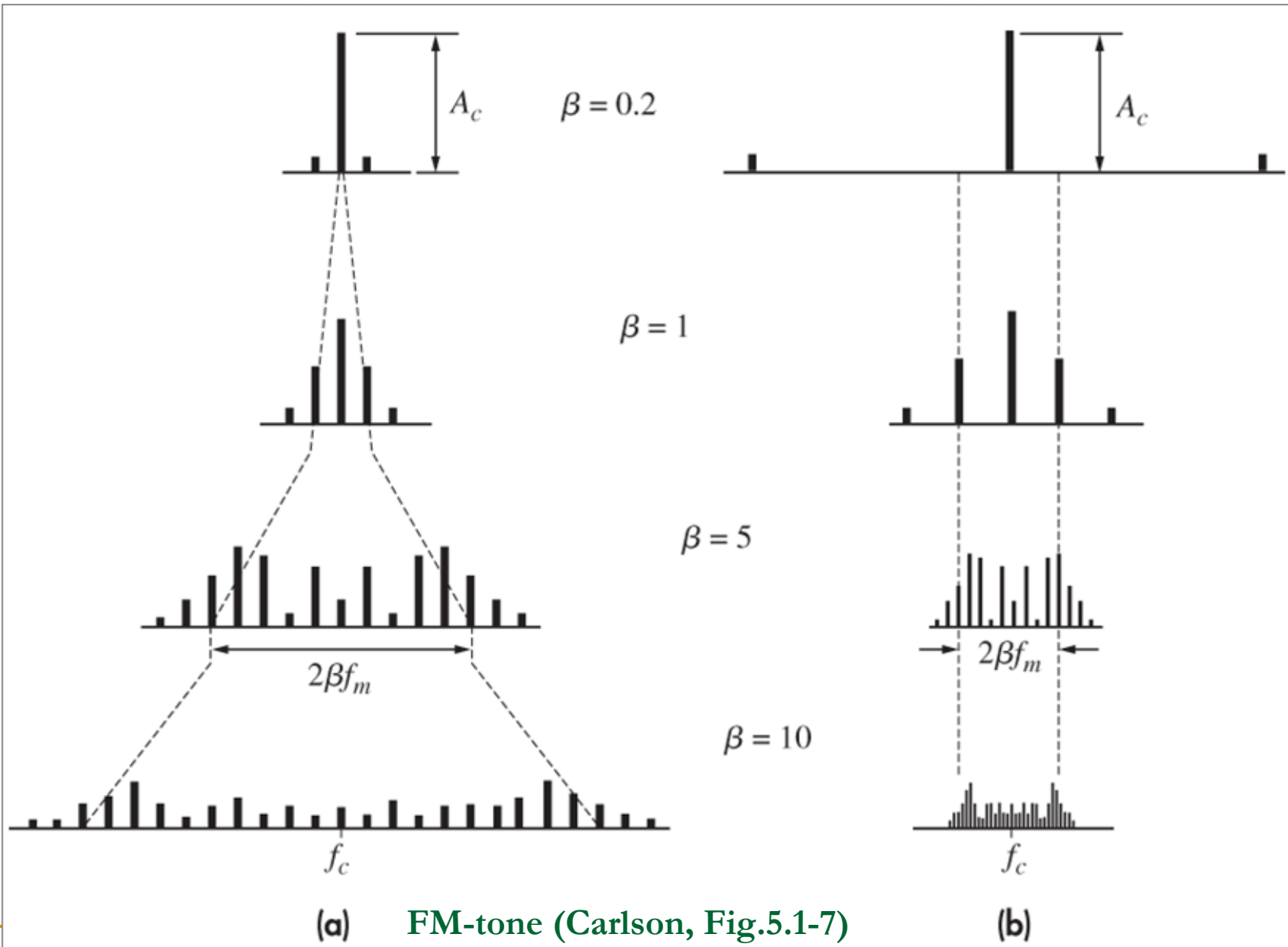


Figure 3.26

Amplitude spectrum of an FM complex envelope signal for increasing β and decreasing f_m .



Power of Angle-Mod Signals

$$\begin{aligned}\langle x_c^2(t) \rangle &= A_C^2 \left\langle \left[\sum_n J_n(\beta) \cos(\omega_c + n\omega_m)t \right]^2 \right\rangle \quad [\text{cross terms are zero}] \\ &= \frac{1}{2} A_C^2 \sum_n J_n^2(\beta) = \frac{1}{2} A_C^2.\end{aligned}$$

Or,

$$\begin{aligned}\langle x_c^2(t) \rangle &= \langle (A_C \cos(\omega_c t + \beta \sin \omega_m t))^2 \rangle \\ &= \frac{1}{2} A_C^2 + \frac{A_C^2}{2} \langle \cos 2(\omega_c t + \beta \sin \omega_m t) \rangle = \frac{1}{2} A_C^2.\end{aligned}$$

- Guess the answer? (*Hint: Waveform*)
- In general, if $m(t)$ has little dc power, this is true.

BW of Angle-Mod Signals

- Small β , $J_n(\beta) \sim 0$, for $n \geq 2 \rightarrow \text{BW} \sim 2W$.
- Large β , find the significant coeffs that contain most of the signal power.
- Define: “**power ratio**” $\Pr \square \frac{k \text{ component power}}{\text{total power}} = \frac{\frac{1}{2} A_c^2 \sum_{n=-k}^k J_n^2(\beta)}{\frac{1}{2} A_c^2}$

$$= J_0^2(\beta) + 2 \sum_{n=1}^k J_n^2(\beta)$$

- Ex: 98% power BW $\sim 2(\beta + 1)f_m$ for single tone

- Define: “**deviation ratio**”

$$D \square \frac{\text{Peak frequency deviation}}{\text{BW of } m(t)} = \frac{\frac{1}{2\pi} \max_t \left| \frac{d\phi(t)}{dt} \right|}{W} = \frac{f_d}{W} (\max |m(t)|),$$

then $\text{BW} \approx 2(D + 1)W$. (Carson's rule)

- $J_n(\beta) \approx \frac{\beta^n}{2^n n!}$ for large n Thus, $\lim_{n \rightarrow \infty} J_n(\beta) = 0$

For PM: $\phi(t) = K_p m(t)$

Special case: $m(t) = A \sin w_m t \rightarrow \frac{d\phi(t)}{dt} = K_p A w_m \cos w_m t$

$$\max_t \left| \frac{d\phi(t)}{dt} \right| = K_p A w_m \Rightarrow \text{Let } \beta = K_p A, \quad D = \frac{\beta f_m}{W} = \beta$$

For FM: $\frac{d\phi(t)}{dt} = K_f m(t) = 2\pi f_d m(t) \quad D = \frac{f_d}{W} (\max_t |m(t)|)$

Special case: $m(t) = A \cos w_m t \rightarrow \max_t |m(t)| = A$

$$\Rightarrow \text{Let } \beta = \frac{A f_d}{f_m} \quad D = \frac{A f_d}{f_m} = \beta$$

(i) $D \ll 1$, $BW \approx 2W$ Narrowband angle-mod signal.

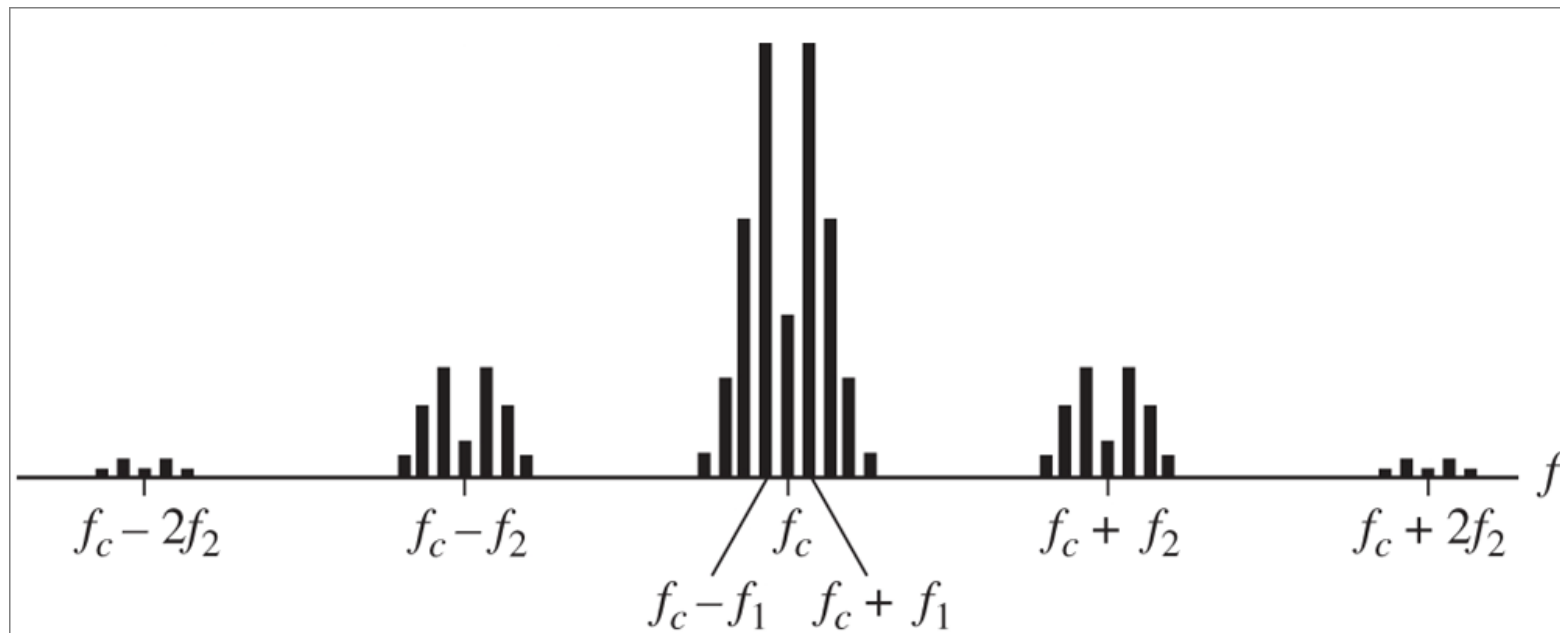
(ii) $D \gg 1$, $BW \approx 2DW = 2f_d(\max|m(t)|)$ Wideband angle-mod signal

Remark: Typical value of β for FM ≈ 5 .

FM with Multi-Tone Message

(B) Two-tone case: $m(t)=A\cos(2\pi f_1t)+B\cos(2\pi f_2t)$

- $x_c(t)$ contains freq components at the sum and difference freqs of the modulating tones and *their harmonics*. (Carlson, Fig.5.1-9) (Z&T, p.151)



FM Signal Generation

- **Indirect FM:** narrowband-to-wideband conversion
- Two stages: 1) narrowband FM
2) frequency multiplier

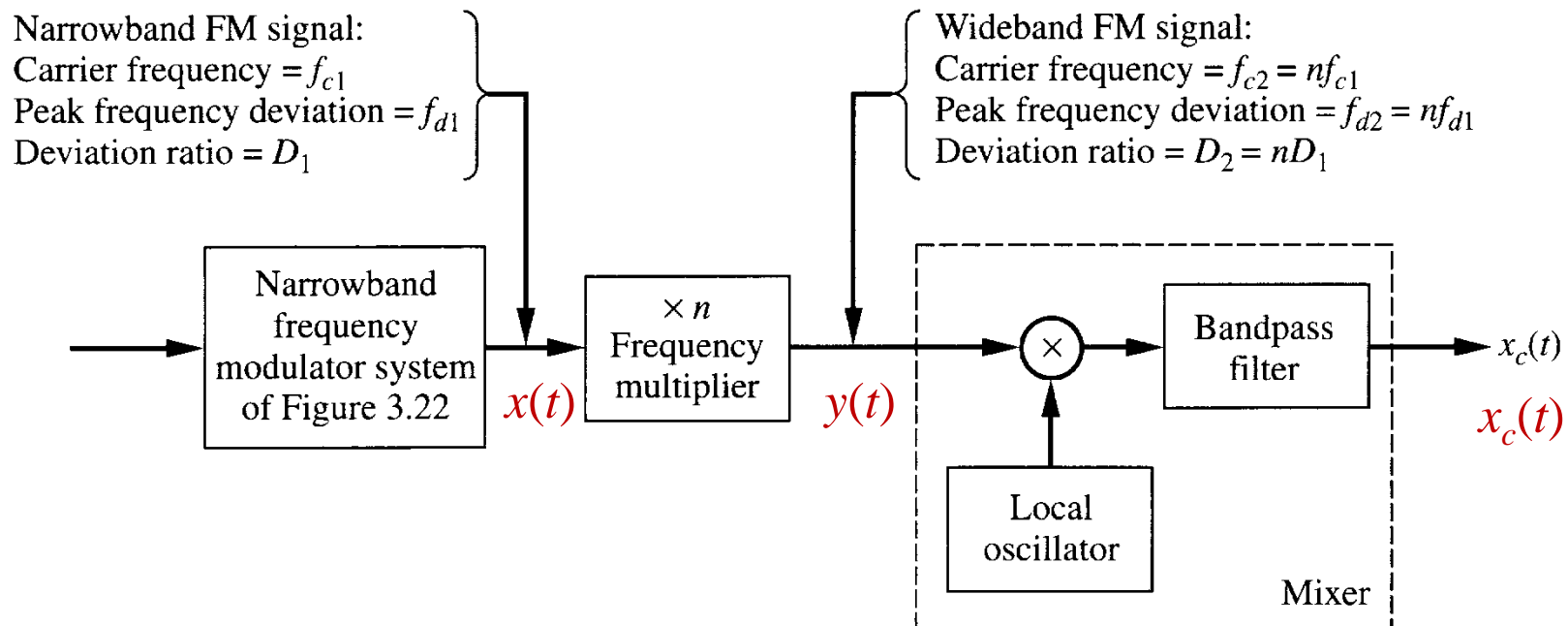


Figure 3.31

Frequency modulation utilizing narrowband-to-wideband conversion.

Indirect FM

1) Narrowband FM output: f_{c1}

$$x(t) = A_c \cos(2\pi f_0 t + \phi(t))$$

2) Freq multiplier output: (a nonlinear device) $f_{c2} = n f_{c1}$

$$y(t) = A_c \cos(2\pi n f_0 t + n\phi(t))$$

3) Mixer: frequency shift to f_c

Let the LO (local oscillator) be $e_{LO}(t) = 2\cos(2\pi f_{LO} t)$

Either $f_c = n f_0 + f_{LO}$ or $f_c = n f_0 - f_{LO}$

$$e(t) = A_c \cos[2\pi(n f_0 + f_{LO})t + n\phi(t)]$$

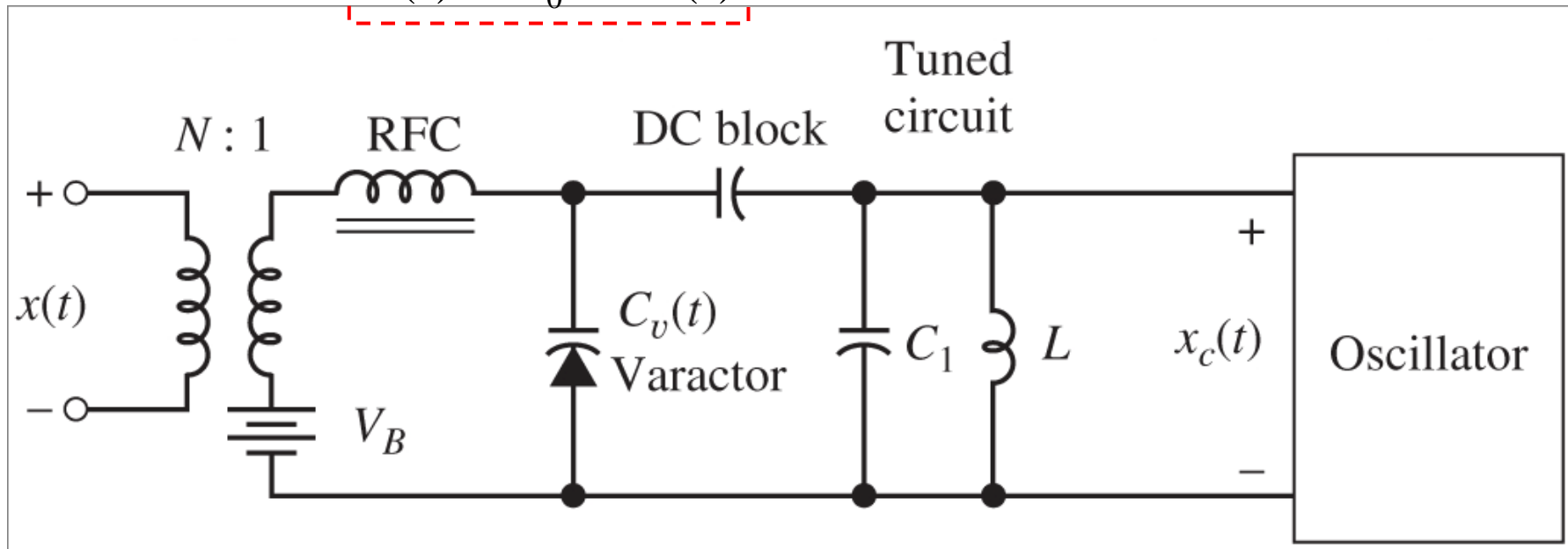
$$+ A_c \cos[2\pi(n f_0 - f_{LO})t + n\phi(t)]$$

$$\rightarrow \mathbf{BPF} \rightarrow x_c(t) = A_c \cos[2\pi f_c t + n\phi(t)]$$

Direct FM

- Use **voltage-controlled oscillator (VCO)** such as *variable-reactance* device (Carlson, p.233~)
- A signal-controlled capacitance device (varactor diode)

$$C(t) = C_0 + Cx(t)$$



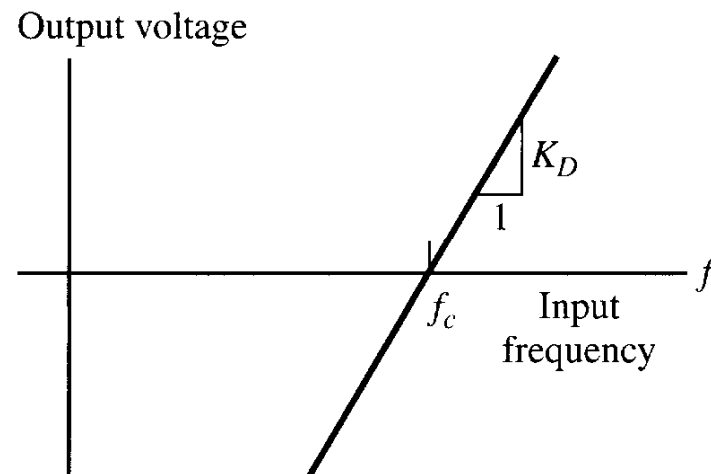
FM Signal Demodulation

- **Ideal frequency discriminator:** a device that yields an output proportional to the frequency deviation of the input.

Received signal: $x_r(t) = A_c \cos(\omega_c t + \phi(t))$.

$$\text{Discriminator: } y_D(t) = \frac{1}{2\pi} K_D \frac{d\phi(t)}{dt}.$$

Figure 3.32
Ideal discriminator characteristic.



FM Demodulator (Approximation)

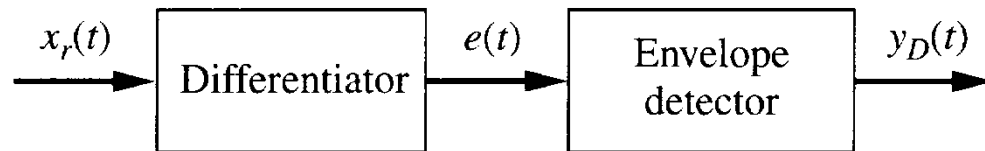


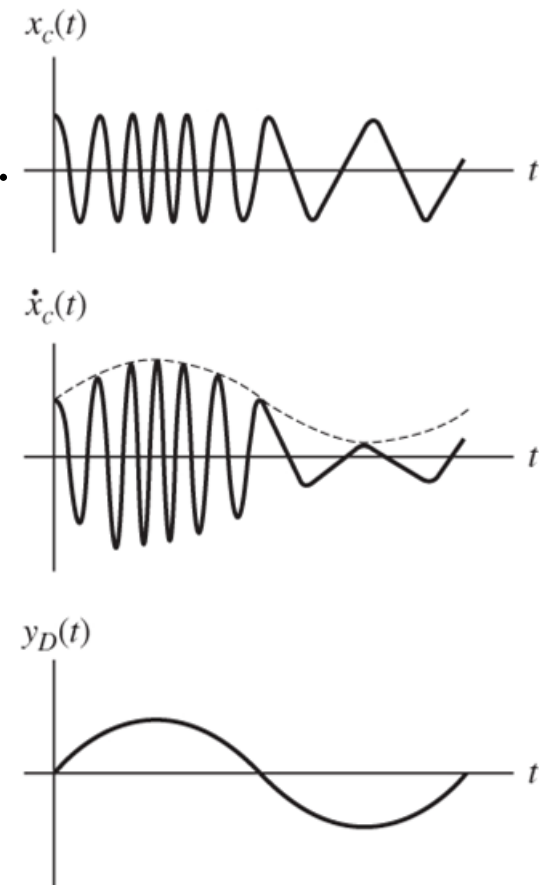
Figure 3.33

Frequency modulation discriminator.

$$e(t) = \frac{dx_r(t)}{dt} = -A_c \left(\omega_c + \frac{d\phi(t)}{dt} \right) \sin(\omega_c t + \phi(t)).$$

$y_D(t)$ = output of envelope detector

$$= A_c \frac{d\phi(t)}{dt} = 2\pi A_c f_d m(t).$$



(Carlson, Fig.5.3-7)

FM Demodulator (2)

- To reduce the channel noise effect, an amplitude limiter and a BPF are placed before the differentiator --- a **bandpass limiter**.

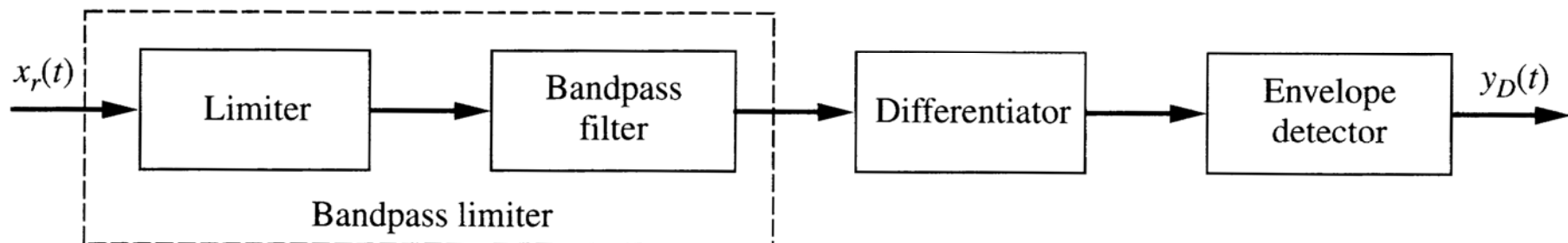


Figure 3.34

Frequency modulation discriminator with bandpass limiter.

Discriminator Implementation

- A “differentiation” operation

1) Time-delay:

$$e(t) = x_r(t) - x_r(t - \tau),$$

for small τ

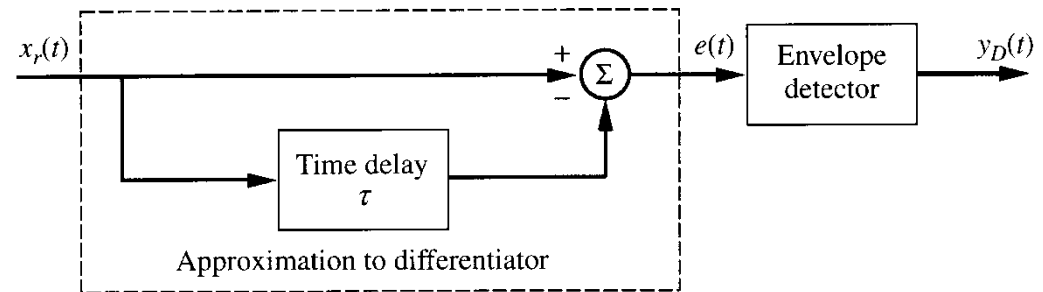


Figure 3.35

Discriminator implementation using delay and envelope detection.

2) RC network:

$$H(f) = \frac{R}{R + \frac{1}{j2\pi fC}} = \frac{j2\pi fRC}{1 + j2\pi fRC} \approx j2\pi fRC, \text{ for small } RC \ll 1$$

Disadvantage: Small $K_D \sim RC \rightarrow$ not practical

RC Network Differentiator

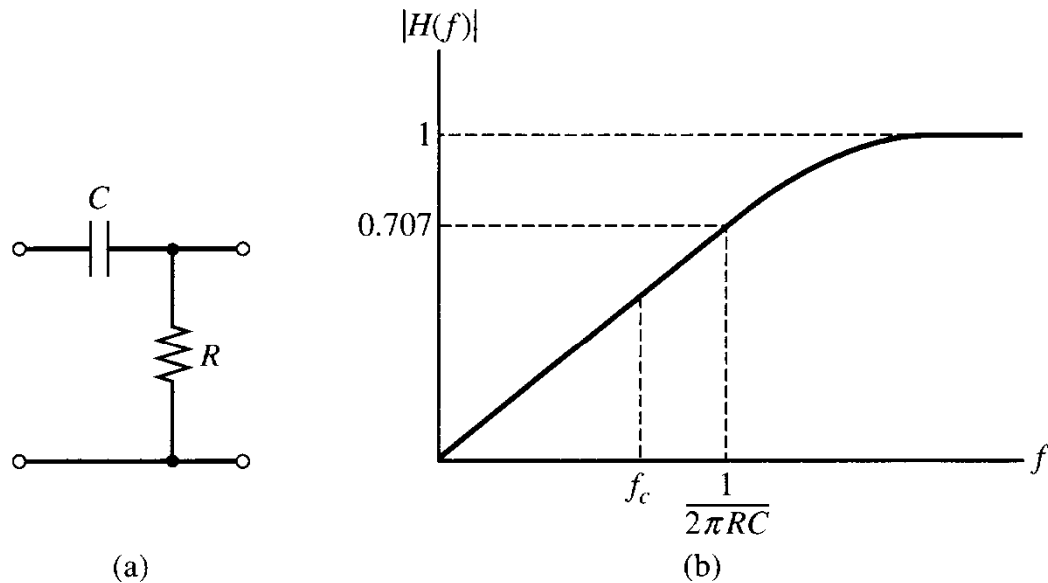
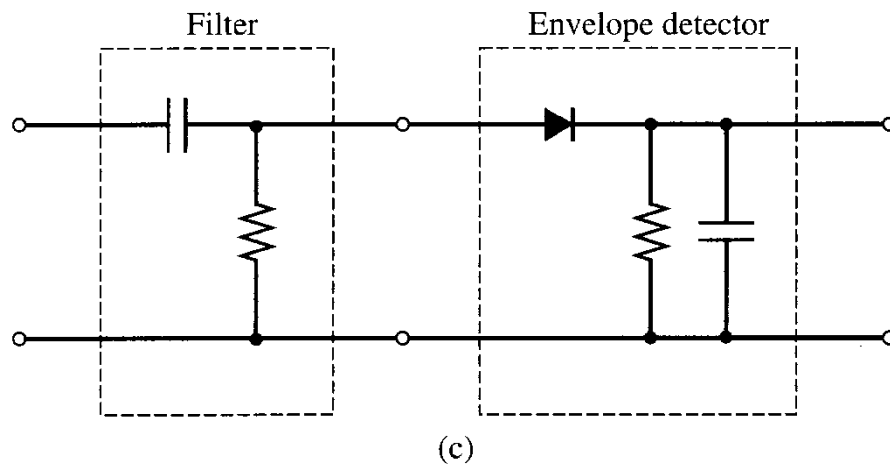


Figure 3.36
Implementation of a simple discriminator. (a) RC network. (b) Transfer function. (c) Simple discriminator.

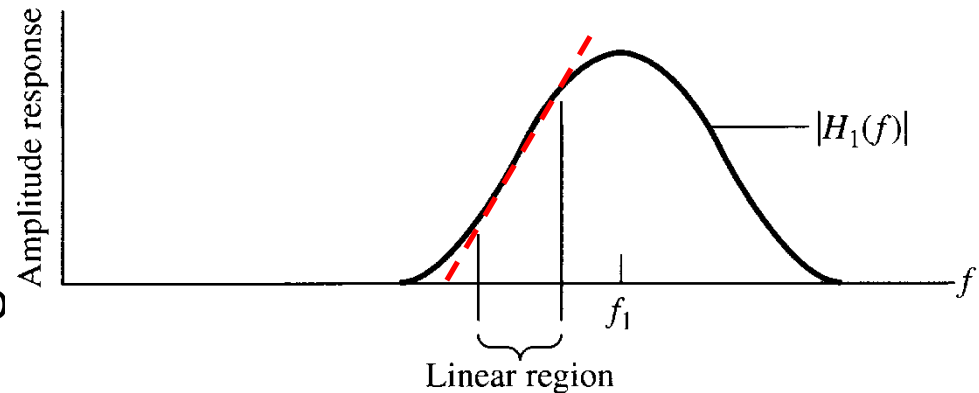


Discriminator Implementation (2)

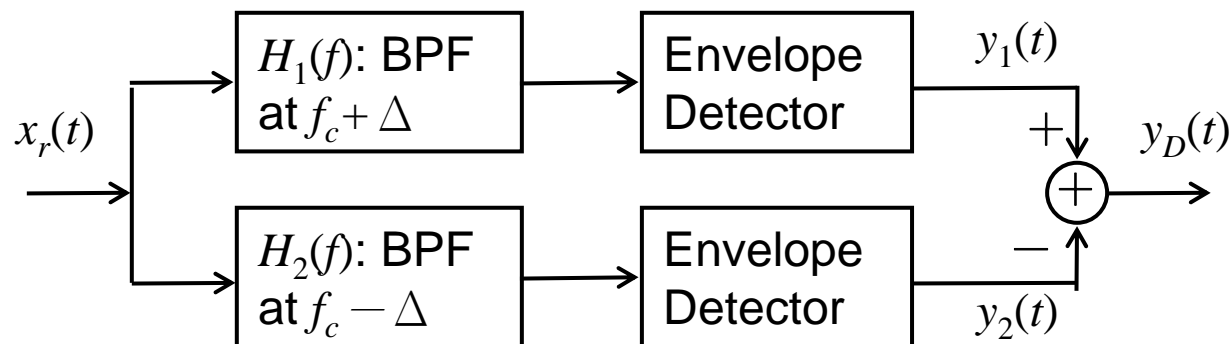
3) BPF

Disadv: a) Small linear region

b) Has dc bias ($H(f)$ should be 0 at $f=0$)



4) Balanced discriminator: Two BPFs



$$y_D(t) = y_1(t) - y_2(t)$$

=envelope of IFT

$$[X_r(f)(|H_1(f)| - |H_2(f)|)]$$

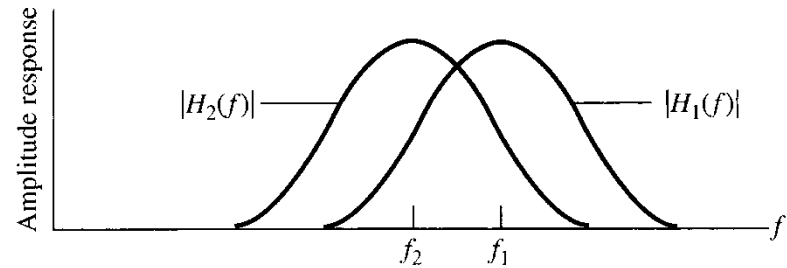
Balanced Discriminator

■ *Adv:*

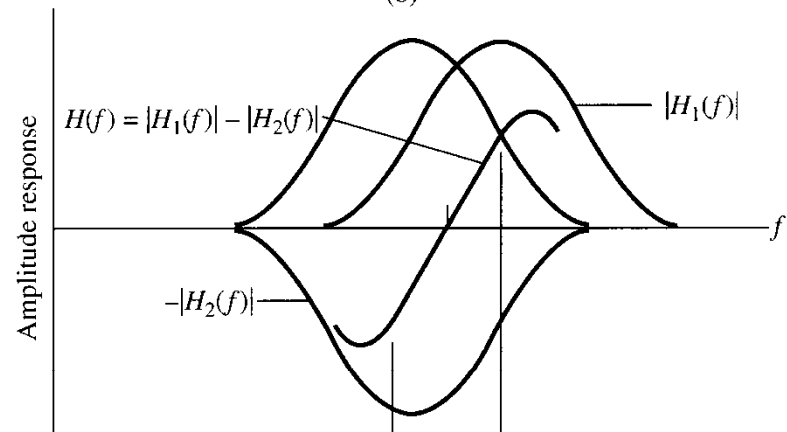
a) Wider linear range

$$(H(f) = |H_1(f)| - |H_2(f)|)$$

b) No dc bias ($H(f=f_c) = 0$)

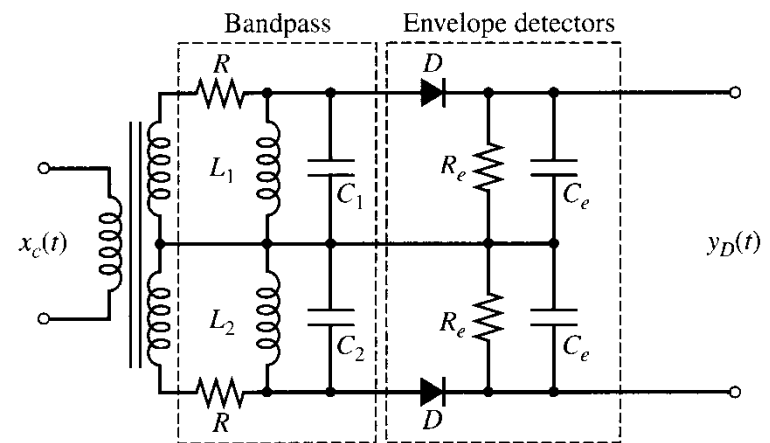


(b)



Linear region

(c)



(d)