

3.1 The baseline performance (in cycles, per loop iteration) of the code sequence in Figure 3.48, if no new instruction's execution could be initiated until the previous instruction's execution had completed, is 40. See Figure S.2. Each instruction requires one clock cycle of execution (a clock cycle in which that instruction, and only that instruction, is occupying the execution units; since every instruction must execute, the loop will take at least that many clock cycles). To that base number, we add the extra latency cycles. Don't forget the branch shadow cycle.

Loop:	LD	F2,0(Rx)	1 + 4
	DIVD	F8,F2,F0	1 + 12
	MULTD	F2,F6,F2	1 + 5
	LD	F4,0(Ry)	1 + 4
	ADD	F4,F0,F4	1 + 1
	ADD	F10,F8,F2	1 + 1
	ADDI	Rx,Rx,#8	1
	ADDI	Ry,Ry,#8	1
	SD	F4,0(Ry)	1 + 1
	SUB	R20,R4,Rx	1
	BNZ	R20,Loop	1 + 1
			-----
		cycles per loop iter	40

**Figure S.2** Baseline performance (in cycles, per loop iteration) of the code sequence in Figure 3.48.

3.2 How many cycles would the loop body in the code sequence in Figure 3.48 require if the pipeline detected true data dependencies and only stalled on those, rather than blindly stalling everything just because one functional unit is busy? The answer is 25, as shown in Figure S.3. Remember, the point of the extra latency cycles is to allow an instruction to complete whatever actions it needs, in order to produce its correct output. Until that output is ready, no dependent instructions can be executed. So the first LD must stall the next instruction for three clock cycles. The MULTD produces a result for its successor, and therefore must stall 4 more clocks, and so on.

Loop:	LD	F2,0(Rx)	1 + 4
	<stall>		
	<stall>		
	<stall>		
	<stall>		
	DIVD	F8,F2,F0	1 + 12
	MULTD	F2,F6,F2	1 + 5
	LD	F4,0(Ry)	1 + 4
	<stall due to LD latency>		
	<stall due to LD latency>		
	<stall due to LD latency>		
	<stall due to LD latency>		
	ADD	F4,F0,F4	1 + 1
	<stall due to ADD latency>		
	<stall due to DIVD latency>		
	<stall due to DIVD latency>		
	<stall due to DIVD latency>		
	<stall due to DIVD latency>		
	ADD	F10,F8,F2	1 + 1
	ADDI	Rx,Rx,#8	1
	ADDI	Ry,Ry,#8	1
	SD	F4,0(Ry)	1 + 1
	SUB	R20,R4,Rx	1
	BNZ	R20,Loop	1 + 1
	<stall branch delay slot>		
			-----
		cycles per loop iter	25

**Figure S.3**

- 3.3 Consider a multiple-issue design. Suppose you have two execution pipelines, each capable of beginning execution of one instruction per cycle, and enough fetch/decode bandwidth in the front end so that it will not stall your execution. Assume results can be immediately forwarded from one execution unit to another, or to itself. Further assume that the only reason an execution pipeline would stall is to observe a true data dependency. Now how many cycles does the loop require? The answer is 22, as shown in Figure S.4. The LD goes first, as before, and the DIVD must wait for it through 4 extra latency cycles. After the DIVD comes the MULTD, which can run in the second pipe along with the DIVD, since there's no dependency between them. (Note that they both need the same input, F2, and they must both wait on F2's readiness, but there is no constraint between them.) The LD following the MULTD does not depend on the DIVD nor the MULTD, so had this been a superscalar-order-3 machine,

	Execution pipe 0		Execution pipe 1	
<b>Loop:</b>	<b>LD</b>	<b>F2,0(Rx)</b>	<b>;</b>	<b>&lt;nop&gt;</b>
	<stall for LD latency>		<b>;</b>	<b>&lt;nop&gt;</b>
	<stall for LD latency>		<b>;</b>	<b>&lt;nop&gt;</b>
	<stall for LD latency>		<b>;</b>	<b>&lt;nop&gt;</b>
	<stall for LD latency>		<b>;</b>	<b>&lt;nop&gt;</b>
	<b>DIVD</b>	<b>F8,F2,F0</b>	<b>;</b>	<b>MULTD F2,F6,F2</b>
	<b>LD</b>	<b>F4,0(Ry)</b>	<b>;</b>	<b>&lt;nop&gt;</b>
	<stall for LD latency>		<b>;</b>	<b>&lt;nop&gt;</b>
	<stall for LD latency>		<b>;</b>	<b>&lt;nop&gt;</b>
	<stall for LD latency>		<b>;</b>	<b>&lt;nop&gt;</b>
	<stall for LD latency>		<b>;</b>	<b>&lt;nop&gt;</b>
	<b>ADD</b>	<b>F4,F0,F4</b>	<b>;</b>	<b>&lt;nop&gt;</b>
	<stall due to DIVD latency>		<b>;</b>	<b>&lt;nop&gt;</b>
	<stall due to DIVD latency>		<b>;</b>	<b>&lt;nop&gt;</b>
	<stall due to DIVD latency>		<b>;</b>	<b>&lt;nop&gt;</b>
	<stall due to DIVD latency>		<b>;</b>	<b>&lt;nop&gt;</b>
	<stall due to DIVD latency>		<b>;</b>	<b>&lt;nop&gt;</b>
	<stall due to DIVD latency>		<b>;</b>	<b>&lt;nop&gt;</b>
	<b>ADDD</b>	<b>F10,F8,F2</b>	<b>;</b>	<b>ADDI Rx,Rx,#8</b>
	<b>ADDI</b>	<b>Ry,Ry,#8</b>	<b>;</b>	<b>SD F4,0(Ry)</b>
	<b>SUB</b>	<b>R20,R4,Rx</b>	<b>;</b>	<b>BNZ R20,Loop</b>
	<b>&lt;nop&gt;</b>		<b>;</b>	<b>&lt;stall due to BNZ&gt;</b>
	cycles per loop iter 22			

**Figure S.4** Number of cycles required per loop.

that LD could conceivably have been executed concurrently with the DIVD and the MULTD. Since this problem posited a two-execution-pipe machine, the LD executes in the cycle following the DIVD/MULTD. The loop overhead instructions at the loop's bottom also exhibit some potential for concurrency because they do not depend on any long-latency instructions.

3.4 Possible answers:

1. If an interrupt occurs between  $N$  and  $N + 1$ , then  $N + 1$  must not have been allowed to write its results to any permanent architectural state. Alternatively, it might be permissible to delay the interrupt until  $N + 1$  completes.
2. If  $N$  and  $N + 1$  happen to target the same register or architectural state (say, memory), then allowing  $N$  to overwrite what  $N + 1$  wrote would be wrong.
3.  $N$  might be a long floating-point op that eventually traps.  $N + 1$  cannot be allowed to change arch state in case  $N$  is to be retried.

Long-latency ops are at highest risk of being passed by a subsequent op. The DIVD instr will complete long after the LD F4,0(Ry), for example.

- 3.5 Figure S.5 demonstrates one possible way to reorder the instructions to improve the performance of the code in Figure 3.48. The number of cycles that this reordered code takes is 20.

Execution pipe 0		Execution pipe 1		
Loop: LD	F2,0(Rx)	;	LD	F4,0(Ry)
	<stall for LD latency>	;		<stall for LD latency>
	<stall for LD latency>	;		<stall for LD latency>
	<stall for LD latency>	;		<stall for LD latency>
	<stall for LD latency>	;		<stall for LD latency>
	DIVD F8,F2,F0	;	ADDD	F4,F0,F4
	MULTD F2,F6,F2	;		<stall due to ADDD latency>
	<stall due to DIVD latency>	;	SD	F4,0(Ry)
	<stall due to DIVD latency>	;	<nop>	#ops: 11
	<stall due to DIVD latency>	;	<nop>	#nops: (20 × 2) – 11 = 29
	<stall due to DIVD latency>	;	ADDI	Rx,Rx,#8
	<stall due to DIVD latency>	;	ADDI	Ry,Ry,#8
	<stall due to DIVD latency>	;	<nop>	
	<stall due to DIVD latency>	;	<nop>	
	<stall due to DIVD latency>	;	<nop>	
	<stall due to DIVD latency>	;	<nop>	
	<stall due to DIVD latency>	;	<nop>	
	<stall due to DIVD latency>	;	SUB	R20,R4,Rx
	ADDD F10,F8,F2	;	BNZ	R20,Loop
	<nop>	;	<stall due to BNZ>	

cycles per loop iter 20

Figure S.5 Number of cycles taken by reordered code.

- 3.6 a. Fraction of all cycles, counting both pipes, wasted in the reordered code shown in Figure S.5:

11 ops out of 2x20 opportunities.

$$1 - 11/40 = 1 - 0.275 = 0.725$$

- b. Results of hand-unrolling two iterations of the loop from code shown in Figure S.6:

c. 
$$\text{Speedup} = \frac{\text{exec time w/o enhancement}}{\text{exec time with enhancement}}$$

$$\text{Speedup} = 20 / (22/2) = 1.82$$

	Execution pipe 0			Execution pipe 1	
<b>Loop:</b>	<b>LD</b>	<b>F2,0(Rx)</b>	;	<b>LD</b>	<b>F4,0(Ry)</b>
	LD	F2,0(Rx)	;	LD	F4,0(Ry)
	<stall for LD latency>		;	<stall for LD latency>	
	<stall for LD latency>		;	<stall for LD latency>	
	<stall for LD latency>		;	<stall for LD latency>	
	<b>DIVD</b>	<b>F8,F2,F0</b>	;	<b>ADD</b>	<b>F4,F0,F4</b>
	DIVD	F8,F2,F0	;	ADD	F4,F0,F4
	<b>MULTD</b>	<b>F2,F0,F2</b>	;	<b>SD</b>	<b>F4,0(Ry)</b>
	MULTD	F2,F0,F2	;	SD	F4,0(Ry)
	<stall due to DIVD latency>		;	<nop>	
	<stall due to DIVD latency>		;	<b>ADDI</b>	<b>Rx,Rx,#16</b>
	<stall due to DIVD latency>		;	<b>ADDI</b>	<b>Ry,Ry,#16</b>
	<stall due to DIVD latency>		;	<nop>	
	<stall due to DIVD latency>		;	<nop>	
	<stall due to DIVD latency>		;	<nop>	
	<stall due to DIVD latency>		;	<nop>	
	<stall due to DIVD latency>		;	<nop>	
	<stall due to DIVD latency>		;	<nop>	
	<stall due to DIVD latency>		;	<nop>	
	<b>ADD</b>	<b>F10,F8,F2</b>	;	<b>SUB</b>	<b>R20,R4,Rx</b>
	ADD	F10,F8,F2	;	<b>BNZ</b>	<b>R20,Loop</b>
	<nop>		;	<stall due to BNZ>	
	cycles per loop iter 22				

**Figure S.6** Hand-unrolling two iterations of the loop from code shown in Figure S.5.

- 3.10 An example of an event that, in the presence of self-draining pipelines, could disrupt the pipelining and yield wrong results is shown in Figure S.10.

	alu0	alu1	ld/st	ld/st	br
Clock cycle 1	ADDI R11, R3, #2		LW R4, 0(R0)		
2	ADDI R2, R2, #16	ADDI R20, R0, #2	LW R4, 0(R0)	LW R5, 8(R1)	
3				LW R5, 8(R1)	
4	ADDI R10, R4, #1				
5	ADDI R10, R4, #1		SW R7, 0(R6)	SW R9, 8(R8)	
6		SUB R4, R3, R2	SW R7, 0(R6)	SW R9, 8(R8)	
7					BNZ R4, Loop

**Figure S.10** Example of an event that yields wrong results. What could go wrong with this? If an interrupt is taken between clock cycles 1 and 4, then the results of the LW at cycle 2 will end up in R1, instead of the LW at cycle 1. Bank stalls and ECC stalls will cause the same effect—pipes will drain, and the last writer wins, a classic WAW hazard. All other “intermediate” results are lost.

3.11 See Figure S.11. The convention is that an instruction does not enter the execution phase until all of its operands are ready. So the first instruction, LW R3,0(R0), marches through its first three stages (F, D, E) but that M stage that comes next requires the usual cycle plus two more for latency. Until the data from a LD is available at the execution unit, any subsequent instructions (especially that ADDI R1, R1, #1, which depends on the 2nd LW) cannot enter the E stage, and must therefore stall at the D stage.

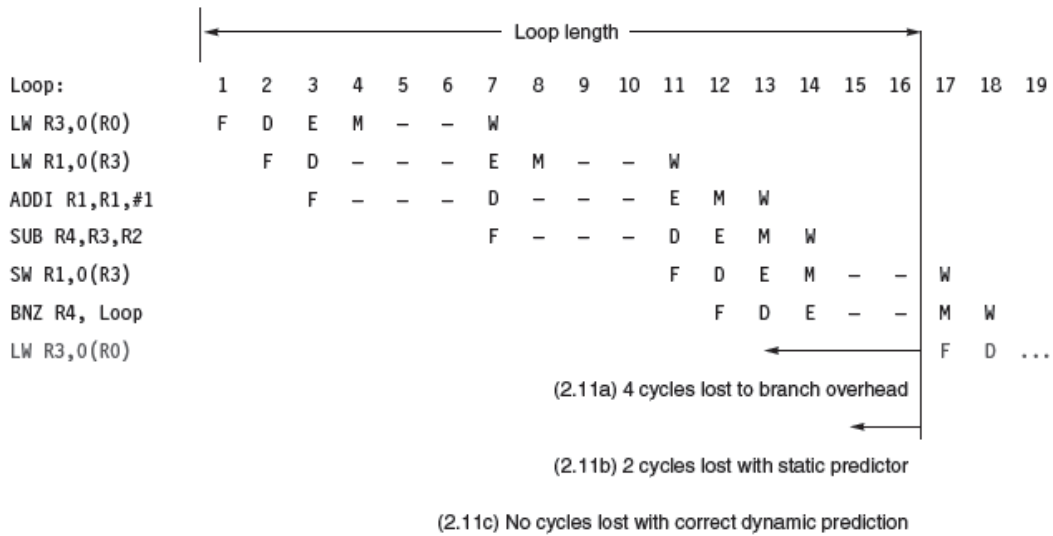


Figure S.11 Phases of each instruction per clock cycle for one iteration of the loop.

(a)

a. See Figure S.18.

Clock cycle	Unscheduled code		Scheduled code	
1	DADDIU	R4,R1,#800	DADDIU	R4,R1,#800
2	L.D	F2,0(R1)	L.D	F2,0(R1)
3	stall		L.D	F6,0(R2)
4	MUL.D	F4,F2,F0	MUL.D	F4,F2,F0
5	L.D	F6,0(R2)	DADDIU	R1,R1,#8
6	stall		DADDIU	R2,R2,#8
	stall		DSLTU	R3,R1,R4
	stall		stall	
	stall		stall	
7	ADD.D	F6,F4,F6	ADD.D	F6,F4,F6
8	stall		stall	
9	stall		stall	
10	stall		BNEZ	R3,foo
11	S.D	F6,0(R2)	S.D	F6,-8(R2)
12	DADDIU	R1,R1,#8		
13	DADDIU	R2,R2,#8		
14	DSLTU	R3,R1,R4		
15	stall			
16	BNEZ	R3,foo		
17	stall			

**Figure S.18** The execution time per element for the unscheduled code is 16 clock cycles and for the scheduled code is 10 clock cycles. This is 60% faster, so the clock must be 60% faster for the unscheduled code to match the performance of the scheduled code on the original hardware.

(b)

b. See Figure S.19.

Clock cycle	Scheduled code	
1	DADDIU	R4,R1,#800
2	L.D	F2,0(R1)
3	L.D	F6,0(R2)
4	MUL.D	F4,F2,F0

**Figure S.19** The code must be unrolled three times to eliminate stalls after scheduling.

5	L.D	F2,8(R1)
6	L.D	F10,8(R2)
7	MUL.D	F8,F2,F0
8	L.D	F2,8(R1)
9	L.D	F14,8(R2)
10	MUL.D	F12,F2,F0
11	ADD.D	F6,F4,F6
12	DADDIU	R1,R1,#24
13	ADD.D	F10,F8,F10
14	DADDIU	R2,R2,#24
15	DSLTU	R3,R1,R4
16	ADD.D	F14,F12,F14
17	S.D	F6,-24(R2)
18	S.D	F10,-16(R2)
19	BNEZ	R3,foo
20	S.D	F14,-8(R2)

**Figure S.19** *Continued*

## 3.14

(c)

c. See Figures S.20 and S.21.

Unrolled 6 times:

Cycle	Memory reference 1	Memory reference 2	FP operation 1	FP operation 2	Integer operation/branch
1	L.D F1,0(R1)	L.D F2,8(R1)			
2	L.D F3,16(R1)	L.D F4,24(R1)			
3	L.D F5,32(R1)	L.D F6,40(R1)	MUL.D F1,F1,F0	MUL.D F2,F2,F0	
4	L.D F7,0(R2)	L.D F8,8(R2)	MUL.D F3,F3,F0	MUL.D F4,F4,F0	
5	L.D F9,16(R2)	L.D F10,24(R2)	MUL.D F5,F5,F0	MUL.D F6,F6,F0	
6	L.D F11,32(R2)	L.D F12,40(R2)			
7					DADDIU R1,R1,48
8					DADDIU R2,R2,48

**Figure S.20** 15 cycles for 34 operations, yielding 2.67 issues per clock, with a VLIW efficiency of 34 operations for 75 slots = 45.3%. This schedule requires 12 floating-point registers.

9			ADD.D F7,F7,F1	ADD.D F8,F8,F2	
10			ADD.D F9,F9,F3	ADD.D F10,F10,F4	
11			ADD.D F11,F11,F5	ADD.D F12,F12,F6	
12					DSLTI R3,R1,R4
13	S.D F7,-48(R2)	S.D F8,-40(R2)			
14	S.D F9,-32(R2)	S.D F10,-24(R2)			
15	S.D F11,-16(R2)	S.D F12,-8(R2)			BNEZ R3,foo

**Figure S.20** Continued



Unrolled 10 times:

Cycle	Memory reference 1	Memory reference 2	FP operation 1	FP operation 2	Integer operation/branch
1	L.D F1,0(R1)	L.D F2,8(R1)			
2	L.D F3,16(R1)	L.D F4,24(R1)			
3	L.D F5,32(R1)	L.D F6,40(R1)	MUL.D F1,F1,F0	MUL.D F2,F2,F0	
4	L.D F7,48(R1)	L.D F8,56(R1)	MUL.D F3,F3,F0	MUL.D F4,F4,F0	
5	L.D F9,64(R1)	L.D F10,72(R1)	MUL.D F5,F5,F0	MUL.D F6,F6,F0	
6	L.D F11,0(R2)	L.D F12,8(R2)	MUL.D F7,F7,F0	MUL.D F8,F8,F0	
7	L.D F13,16(R2)	L.D F14,24(R2)	MUL.D F9,F9,F0	MUL.D F10,F10,F0	DADDIU R1,R1,48
8	L.D F15,32(R2)	L.D F16,40(R2)			DADDIU R2,R2,48
9	L.D F17,48(R2)	L.D F18,56(R2)	ADD.D F11,F11,F1	ADD.D F12,F12,F2	
10	L.D F19,64(R2)	L.D F20,72(R2)	ADD.D F13,F13,F3	ADD.D F14,F14,F4	
11			ADD.D F15,F15,F5	ADD.D F16,F16,F6	
12			ADD.D F17,F17,F7	ADD.D F18,F18,F8	DSLTI R3,R1,R4
13	S.D F11,-80(R2)	S.D F12,-72(R2)	ADD.D F19,F19,F9	ADD.D F20,F20,F10	
14	S.D F13,-64(R2)	S.D F14,-56(R2)			
15	S.D F15,-48(R2)	S.D F16,-40(R2)			
16	S.D F17,-32(R2)	S.D F18,-24(R2)			
17	S.D F19,-16(R2)	S.D F20,-8(R2)			BNEZ R3,foo

**Figure S.21** 17 cycles for 54 operations, yielding 3.18 issues per clock, with a VLIW efficiency of 54 operations for 85 slots = 63.5%. This schedule requires 20 floating-point registers.